

Stochastic Differential Graphon Games and SDEs driven by a Continuum of Independent Brownian Motions

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SAUCY2021, April 6, 2021

Credits

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Stochastic Graphon Games
Mathematics of Operations Research 2020
- **A. Aurell, R.C., and M. Laurière**
Linear Quadratic Stochastic Graphon Games
in preparation

Outline

- 1 WHY GRAPHON GAMES
- 2 FINITE PLAYER MODEL
- 3 GAMES WITH A CONTINUUM OF PLAYERS
- 4 DYNAMIC GAME MODELS
- 5 LINEAR QUADRATIC STOCHASTIC GRAPHON GAMES
- 6 APPROXIMATIONS BY N -PLAYER NETWORK GAMES

Motivation from Classical MFG Examples

- Where do **Pierre-Louis** and **Jean Michel** *put their towels on the beach?*:
 - Affinities are not *uniformly distributed*
 - One may want to avoid *some people*

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- Game models for **fisheries**
 - Fisheries interact *only* with fisheries which harvest from the same or connecting bodies of water
- **Cournot Competition**
 - Producers compete *only* when consumer bases overlap and products are *exchangeable*

Definition of a N -player Static Network Game

- N players $\{1, 2, \dots, N\}$
- $W = [w_{i,j}]_{i,j=1,\dots,N}$ an $N \times N$ symmetric matrix of real numbers;
 - $w_{i,j}$ weight quantifying the strength of the **interaction** between players i and j
- A (closed convex subset of \mathbb{R}^k) set of admissible actions
 - $A = \mathbb{R}^k$ for the purpose of this talk
- **Strategy** profiles $\alpha = (\alpha_1, \dots, \alpha_N) \in A^N$
- Idiosyncratic **noise**, i.i.d mean-zero random variables ξ_1, \dots, ξ_N with order 2 distribution μ_0
- **State** of a player $X_{\alpha,z,\xi} = b(\alpha, z) + \xi$ when
 - taking action $\alpha \in A$
 - feeling the impact of other states through the aggregate z
 - incurring idiosyncratic random shock ξ

where $b : A \times \mathbb{R} \ni (\alpha, z) \mapsto b(\alpha, z) \in \mathbb{R}$ is Lipschitz w.r.t. (α, z) , with Lipschitz constants $c_\alpha > 0$ and $c_z \in (0, 1)$.

- **Interaction through Aggregate:**

$$Z_N \alpha = \left(\frac{1}{N} \sum_{j=1}^N w_{i,j} X_{\alpha_j, Z_j, \xi_j} \right)_{i=1,\dots,N}, \quad \alpha \in A^N \quad (1)$$

- **Costs + notions of Equilibrium**

Stochastic Graphon Game: limit $N \rightarrow \infty$

Assumption: Graph $W = [w_{i,j}]_{i,j=1,\dots,N}$ underpinning the interactions is **dense** and **converges** as $N \rightarrow \infty$. **Graphon** w

- Set of players $I = [0, 1]$, $\mathcal{B}(I)$ its Borel σ -field, λ_I Lebesgue measure on $(I, \mathcal{B}(I))$.
- Players **interact** through a **graphon** w
(symmetric real-valued Lebesgue-measurable square-integrable function on $[0, 1] \times [0, 1]$).
- Set A of individual actions same as before.
- A **strategy profile** is a function α which associates to each player $x \in I$ an action $\alpha(x) = \alpha_x$ in $A \subset \mathbb{R}^k$.
- α is admissible ($\alpha \in \mathbb{A}$) if $\alpha \in L^2(I; \mathbb{R}^k) = L^2(I, \mathcal{B}(I), \lambda_I; \mathbb{R}^k)$.
- **Idiosyncratic noise:**
 - $\xi = (\xi_x)_{x \in I}$ is **i.i.d.**
 - **State Equation** $X_{\alpha,z,\xi} = b(\alpha, z) + \xi$ with aggregate

$$[Z\alpha]_x = \int_I w(x, y) X_{\alpha_y, [Z\alpha]_y, \xi_y} \lambda_I(dy), \quad x \in I$$

Obvious Questions

- **Shouldn't $x \mapsto \xi_x$ be measurable?**
- **Shouldn't the aggregate $[Z\alpha]_x$ be deterministic?** (LLN)

Aside: Connections with MFGs

- **Constant Graphon**

$$\exists a \in [0, 1], \forall x, y \in [0, 1], \quad w(x, y) = a$$

If

$$X_{\alpha, z, \xi} = b(\alpha, z) + \xi, \quad \mathcal{J}(\alpha, z) = \mathbb{E}[f(X_{\alpha, z, \xi}, \alpha, z)],$$

Graphon Game = MFG

- **Constant Connection Strength Graphon**

$$\exists a \in [0, 1], \forall x \in [0, 1], \quad \int_{[0,1]} w(x, y) dy = a$$

If the aggregate \mathbf{Z} is well defined, and if there exists a Nash equilibrium $\hat{\alpha}$ for the above MFG with constant a then $\hat{\alpha}(\cdot) = \hat{\alpha}$ is a Nash equilibrium for the graphon game.

- **Piecewise Constant Graphon games = Multi-Population MFGs**

Equilibrium Theory in Macro-Economics & Finance

Huge literature on economic models with *continuum of infinitesimally small firms or agents* e.g.

J. Geanakoplos, I. Karatzas, M. Shubik, W. D. Sudderth

Inflationary equilibrium in a stochastic economy with independent agents
Journal of Mathematical Economics 52 (2014) 1–11

- " ... we consider an economy in which a continuum of agents are subject to idiosyncratic, independent and identically distributed random shocks to their endowments."
- " ... we assume that the integrals

$$\int_I Y_n^\alpha(\omega) d\alpha = Q_n(\omega) = Q$$

are constant across time-periods $n \in \mathbb{N}$ and states $\omega \in \Omega$. We assume further that the random endowments $Y_n(\alpha, \omega)$ are jointly measurable in (α, ω) , where the variable α ranges over the index set $I = [0, 1]$ and the variable ω ranges over the probability space Ω A consequence of our assumptions about the random endowments is that

$$\int_\Omega Y_n(\alpha, \omega) \mathbb{P}(d\omega) = \int_I Y_n(\alpha, \omega) d\alpha = Q."$$

Exact Law of Large Numbers

- **T.F. Bewley** Stationary Monetary Equilibrium with a Continuum of Independently Fluctuating Consumers. Essays in Honor. of Girard Debreu (W. Hildenbrand and A. Mas-Colell, Eds.), (1986) pp. 79-102.
- **K.L. Judd** The law of large numbers with a continuum of IID random variables, J. Econ. Theory 35 (1985) 19–25.
- **M. Feldman, C. Gilles** An expository note on individual risk without aggregate uncertainty, J. Econ. Theory 35 (1985) 26–32.
- **Y.N. Sun** A theory of hyperfinite processes: the complete removal of individual uncertainty via exact LLN, J. Math. Econ. 29 (1998) 419–503.

J. Miao

Competitive equilibria of economies with a continuum of consumers and aggregate shocks

Journal of Economic Theory 128 (2006) 274 – 298

- *".... there are subtle technical problems, pointed out by Judd [20], associated with an environment that has a continuum of agents, e.g., measurability and the law of large numbers."*
- *" there is a difficulty associated with the presence of aggregate shocks. When they are present, aggregate distributions are generally random measures that may be correlated with individual shocks."*

Particle Systems Limits (without Optimization)

Given

- $\{B_x(t)\}_{t \geq 0, x \in I}$ i.i.d. such that $\{B_x(t)\}_{t \geq 0}$ is a Brownian motion for each $x \in I$
- $\{X_x(0)\}_{x \in I}$ i.i.d. with common distribution μ_0
- $(b, \sigma) : \mathbb{R} \times \mathbb{R} \mapsto \mathbb{R}^2$ Lip-1
- $([w_{i,j}^n]_{i,j=1, \dots, n})_{n \geq 0}$ sequence of interaction weights in $[0, 1]$ for n particles

consider the n -particle SDE for $([X_i^n(t)]_{i=1, \dots, n})_{t \geq 0}$

$$X_i^n(t) = X_{i/n}(0) + \int_0^t \frac{1}{n} \sum_{j=1}^n w_{i,j}^n b(X_i^n(s), X_j^n(s)) ds + \int_0^t \frac{1}{n} \sum_{j=1}^n w_{i,j}^n \sigma(X_i^n(s), X_j^n(s)) dB_{i/n}(s),$$

Assume that the graphon W^n defined by

$$W^n\left(\frac{i}{n}, \frac{j}{n}\right) = w_{i,j}^n, \quad \text{and} \quad W^n(x, y) = W^n\left(\frac{\lceil nx \rceil}{n}, \frac{\lceil ny \rceil}{n}\right), \quad x, y \in I$$

converges in the cut metric $W^n \rightarrow W$.

Then for each $0 < T < \infty$

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n \mathbb{E} \left[\sup_{0 \leq t \leq T} |X_i^n(t) - X_{i/n}(t)|^2 \right] = 0$$

where, with the notation $\mu_{x,t} = \mathcal{L}(X_x(t))$,

$$\begin{aligned} X_x(t) &= X_x(0) + \int_0^t \int_I \int_{\mathbb{R}} w(x, y) b(X_x(s), z) \mu_{y,s}(dz) dy ds \\ &\quad + \int_0^t \int_I \int_{\mathbb{R}} w(x, y) \sigma(X_x(s), z) \mu_{y,s}(dz) dy dB_x(s), \quad x \in I. \end{aligned}$$

Remarks on the Previous Limit

Announced / claimed / proved by in several recent arXiv announcements

- **G. Bet, F. Coppini, F. R Nardi**
Weakly interacting oscillators on dense random graphs, arXiv
- **P. E. Caines, M. Huang**
Graphon mean field games and the GMFG equations
- **E. Bayraktar, S. Chakraborty, R. Wu**
Graphon Mean Field Systems

Concerning the equation in red:

- 1 It requires the **joint measurability** of $I \times [0, \infty) \ni (x, t) \mapsto \mu_{x,t} \in \mathcal{P}(\mathbb{R})$
- 2 $(X_x(t))_{t \geq 0}$ and $(X_y(t))_{t \geq 0}$ are **independent** if $x \neq y$ in I
- 3 It does not require the **joint measurability** of $I \times [0, \infty) \times \Omega \ni (x, t, \omega) \mapsto X_x(t, \omega)$

This result could be viewed as

- ◇ a form of **propagation of chaos**
- ◇ a justification of the 2nd approach suggested by **Feldman-Gilles**

Fubini's Extensions

Definition

A probability space $(\Omega \times I, \mathcal{W}, \mathbb{Q})$ extending the usual product space $(\Omega \times I, \mathcal{F} \otimes \mathcal{I}, \mathbb{P} \otimes \lambda)$ is said to be a **Fubini extension** of $(\Omega \times I, \mathcal{F} \otimes \mathcal{I}, \mathbb{P} \otimes \lambda)$ if for any real-valued \mathbb{Q} -integrable function f on $(\Omega \times I, \mathcal{W})$

- (I) the two functions $f_x : \omega \mapsto f(\omega, x)$ and $f_\omega : x \mapsto f(\omega, x)$ are integrable, respectively, on $(\Omega, \mathcal{F}, \mathbb{P})$ for λ -a.e. $x \in I$, and on $(I, \mathcal{I}, \lambda)$ for \mathbb{P} -a.e. $\omega \in \Omega$.
- (II) $\int_\Omega f_x(\omega) d\mathbb{P}$ and $\int_I f_\omega(x) \lambda(dx)$ are integrable, respectively, on $(I, \mathcal{I}, \lambda)$ and $(\Omega, \mathcal{F}, \mathbb{P})$, with

$$\int_{\Omega \times I} f(\omega, x) d\mathbb{Q}(\omega, x) = \int_I \left(\int_\Omega f_x(\omega) d\mathbb{P}(\omega) \right) d\lambda(x) = \int_\Omega (f_\omega(x) d\lambda(x)) d\mathbb{P}(\omega)$$

Theorem (Sun)

Let I be the **unit interval** and S a **Polish space**. There exist

- a probability space $(I, \mathcal{I}, \lambda)$ extending $(I, \mathcal{B}_I, \lambda_I)$
- a probability space $(\Omega, \mathcal{F}, \mathbb{P})$, and a Fubini extension $(\Omega \times I, \mathcal{F} \boxtimes \mathcal{I}, \mathbb{P} \boxtimes \lambda)$ of $(\Omega \times I, \mathcal{F} \otimes \mathcal{I}, \mathbb{P} \otimes \lambda)$ such that
- for any measurable mapping $\mu : (I, \mathcal{I}) \mapsto \mathcal{P}(S)$, there is an $\mathcal{F} \boxtimes \mathcal{I}$ -measurable process $\xi : \Omega \times I \rightarrow S$ such that
 - the random variables $\xi_x = \xi(\cdot, x)$ are **essentially pairwise independent**
 - $\mathbb{P} \circ \xi_x^{-1} = \mu_x$ for λ -a.e. $x \in I$

Brute Force Approach based on Fubini's Extensions

- $I = [0, 1]$, \mathcal{B}_I Borel σ -field, λ_I Lebesgue measure.
- $(I \times \Omega, \mathcal{I} \boxtimes \mathcal{F}, \lambda \boxtimes \mathbb{P})$ **rich Fubini extension**
- μ_0 Wiener measure on $E = C([0, T])$
- $(\xi_x)_{x \in I}$ **essentially pairwise independent** in E with law $\mu_x = \mu_0$ for $x \in I$.
- For $t \in [0, T]$, C_t the coordinate map $E \ni \omega \mapsto C_t(\omega) = \omega(t)$. i.e. $(C_t)_{0 \leq t \leq T}$ is a Brownian motion $(E, \mathcal{B}_E, \mu_0)$
- For $t \geq 0$, and $x \in I$, $B_x(t) = C_t(\xi_x)$
- For each $x \in I$, $\mathbf{B}_x = (B_x(t))_{0 \leq t \leq T}$ is a Brownian motion on $(\Omega, \mathcal{F}, \mathbb{P})$
- $(\mathbf{B}_x)_{x \in I}$ are **essentially pairwise independent** i.e. for λ -almost every $x \in I$ the process \mathbf{B}_x is independent of the process \mathbf{B}_y for λ -almost every $y \in I$.
- For each $x \in I$, $\mathcal{F}_t^x = \sigma\{B_x(s); 0 \leq s \leq t\}$

An admissible strategy profile $\alpha \in \mathbb{A}$ is a measurable and square integrable process on $(I \times \Omega, \mathcal{I} \boxtimes \mathcal{F}, \lambda \boxtimes \mathbb{P})$ with values in $L^2([0, T], dt)$ which is progressive.

- w **graphon**, \mathbf{W} **associated operator** on $L^2(I, \mathcal{B}_I, \lambda_I)$

NB: \mathbf{W} acts on $L^2(I, \mathcal{I}, \lambda)$ since $\int_I w(x, y)f(y)\lambda(dy)$ makes sense for $f \in L^2(I, \mathcal{I}, \lambda)$.

Wishful Thinking

State Dynamics

$$dX_t^x = b(\alpha_t^x, z_t^x)dt + dB_x(t), \quad x \in I$$

where z_t^x is the **aggregate felt by** $x \in I$ **at time** t . Intuitively:

$$z_t^x = \int_I w(x, y) X_t^y \lambda(dy)$$

Costs

$$J^x(\alpha, (\hat{\alpha}^x)^{x \in I}) = \mathbb{E} \left[\int_0^T f(\alpha_t, [Z\hat{\alpha}]_t^x) dt \right], \quad x \in I,$$

with

- $\alpha = (\alpha_t)_{0 \leq t \leq T}$ **strategy** of player $x \in I$
- $(\hat{\alpha}^x)^{x \in I} = (\hat{\alpha}_t^x)_{0 \leq t \leq T}^{x \in I}$ **strategy profile** of all the players
- **aggregate** $[Z\hat{\alpha}]_t^x = \int_I w(x, y) X_t^y \lambda(dy)$

Exact Law of Large Numbers (**Sun, Duffie-Sun**) in the absence of **common aggregate noise**
the aggregates should be deterministic

Search for Nash Equilibria

- Start from $(\hat{\alpha}^x)^{x \in I}$
- Solve for $(X_t^x)_{0 \leq t \leq T}^{x \in I}$ and $([Z\hat{\alpha}]_t^x)_{0 \leq t \leq T}^{x \in I}$
- For a.e. $x \in I$ find $(\alpha_t^{*,x})_{0 \leq t \leq T} = \arg \inf_{\alpha} J^x(\alpha, ([Z\hat{\alpha}]_t^x)_{0 \leq t \leq T}^{x \in I})$
- Check that $(\hat{\alpha}^x)^{x \in I} = (\alpha^{*,x})^{x \in I}$

Same functional analytic tools should work under appropriate assumptions

- Forward / Backward HJB / Kolmogorov system? **Caines-Huang?**
- Pontryagin? Infinite dimensional FBSDEs?

Linear Quadratic Stochastic Graphon Games

Assumptions

- (I) Initial conditions $X_x(0) \in L^2(\Omega \times I; \mathbb{R})$, **e.p.i.**
- (II) The functions $a, b, c : I \rightarrow \mathbb{R}$ are **\mathcal{I} -measurable and bounded**

Theorem

For a fixed admissible strategy profile $\alpha \in \mathbb{A}$, there **exists a unique solution** defined for all $x \in I$ to the graphon SDE system

$$dX_t^{\alpha,x} = (a(x)X_t^{\alpha,x} + b(x)\alpha_t^x + c(x)Z_t^{\alpha,x}) dt + dB_x(t), \quad t \in [0, T],$$

with $X_0^{\alpha,x} = X_x(0)$, where $Z^{\alpha,x}$ is the following **graphon aggregate**

$$Z_t^{\alpha,x} := \int_I w(x,y)X_t^{\alpha,y} \lambda(dy) = [\mathbf{W}X_t^{\alpha,\cdot}](x), \quad t \in [0, T].$$

Moreover, $Z_t^{\alpha,x}$ is **deterministic** !

Proof Strategy

Step 1.

If $z \in L^2_{\mathbb{F}}(\Omega \times I; E)$ and $\alpha \in \mathbb{A}$, then the **stochastic integral equation**

$$X_t^{\alpha, \cdot, z} = X_0^{\alpha, \cdot, z} + \int_0^t (a(\cdot)X_s^{\alpha, \cdot, z} + b(\cdot)\alpha_s + c(\cdot)z_s(\cdot)) ds + B(\cdot)(t), \quad t \in [0, T], \quad X_0^{\alpha, \cdot, z} = \xi$$

has a **unique solution** $X^{\alpha, z} = (X_t^{\alpha, \cdot, z})_{0 \leq t \leq T}$ in $L^2_{\mathbb{F}}(\Omega \times I; E)$.

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Step 2.

For each $\alpha \in \mathbb{A}$, introduce the following mapping:

$$U^\alpha : L^2_{\mathbb{F}}(\Omega \times I; E) \rightarrow L^2_{\mathbb{F}}(\Omega \times I; E),$$
$$z \mapsto U^\alpha z : (\omega, x) \mapsto \left(\int_I w(x, y) X_t^{\alpha, y, z}(\omega) \lambda(dy) \right)_{t \in [0, T]}$$

and show that it is a **strict contraction**

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Proposition

For each **admissible strategy profile** $\alpha \in \mathbb{A}$, the mapping U^α has a **unique fixed point** Z^α

$$Z_t^{\alpha, x} := \int_I w(x, y) X_t^{\alpha, y} \lambda(dy) \quad x \in I, \quad t \in [0, T].$$

which is **deterministic** (by the exact LLN).

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NB: *Result still holds for Lipschitz (non-linear) drift*

Costs & Nash Equilibrium for the Stochastic Graphon Game

Expected cost to player $x \in I$ following the admissible strategy $\beta \in \mathbb{A}(x)$ while λ -a.e. other player use the strategy profile α is given by:

$$J^x(\beta; \alpha) := \mathbb{E} \left[\int_0^T f^x(X_t^{(\alpha^{-x}, \beta), x}, \beta_t, Z_t^{\alpha, x}) dt + h^x(X_T^{(\alpha^{-x}, \beta), x}, Z_T^{\alpha, x}) \right],$$

where for $\alpha \in \mathbb{A}$, $x \in I$ and $\beta \in \mathbb{A}(x)$

$$(\alpha^{-x}, \beta)^y = \begin{cases} \alpha^y, & \text{if } y \neq x \\ \beta, & \text{if } y = x. \end{cases}$$

Remark: $J^x(\beta; \alpha) = \mathcal{J}^x(\hat{\alpha}^x, Z^{\hat{\alpha}, x})$ so:

Definition An **admissible strategy profile** $\hat{\alpha}$ is a graphon game **Nash equilibrium** if it satisfies for all $x \in I$

$$\mathcal{J}^x(\hat{\alpha}^x, Z^{\hat{\alpha}, x}) \leq \mathcal{J}^x(\beta, Z^{\hat{\alpha}, x}), \quad \beta \in \mathcal{A}(x).$$

Stochastic Maximum Principle

Proposition

Assume that for each $x \in I$, the functions f^x and h^x are bounded measurable and that for all $(x, u, z) \in I \times \mathbb{R} \times \mathbb{R}$, $\chi \mapsto f^x(\chi, u, z)$ and $\chi \mapsto h^x(\chi, z)$ are differentiable. Then if it exists, a Nash equilibrium $\hat{\alpha}$ must satisfy

$$\hat{\alpha}_t^x = \arg \inf_{u \in \mathbb{R}} H^x(t, \hat{X}_t^x, u, p_t^x), \quad \text{a.e. } t \in [0, T], \quad \mathbb{P}\text{-a.s.}, \quad (2)$$

for each $x \in I$, with (\hat{X}^x, p^x, q^x) satisfying the Hamiltonian system (adjoint equations)

$$\begin{cases} d\hat{X}_t^x = \partial_p H^x(t, \hat{X}_t^x, \hat{\alpha}_t^x, p_t^x) dt + dB_x(t), & \hat{X}_0^x = \xi^x, \\ dp_t^x = -\partial_\chi H^x(t, \hat{X}_t^x, \hat{\alpha}_t^x, p_t^x) dt + q_t^x dB_x(t), & p_T^x = \partial_\chi h^x(\hat{X}_T^x, \hat{Z}_T^x), \end{cases}$$

where $H^x : [0, T] \times \mathbb{R} \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ is the Hamiltonian of player x

$$H^x(t, \chi, u, p) = f^x(\chi, u, \hat{Z}_t^x) + (a(x)\chi + b(x)u + c(x)\hat{Z}_t^x)p,$$

\hat{Z}_t^x is the graphon aggregate corresponding to \hat{X}_t^x .

If, in addition $(\chi, u) \mapsto f^x(\chi, u, z)$ and $\chi \mapsto h^x(\chi, z)$ are convex, then any $\alpha \in \mathbb{A}$ satisfying (2) for every $x \in I$ is a Nash equilibrium.

Solution of the L-Q Stochastic Graphon Game

Assumptions

$$f^x(u) = \frac{1}{2}u^* C_f(x)u, \quad h^x(v) = \frac{1}{2}v^* C_h(x)v, \quad u \in \mathbb{R}^3, v \in \mathbb{R}^2.$$

for bounded measurable $C_f : I \rightarrow \mathbb{R}_{\text{sym}, \geq 0}^{3 \times 3}$ and $C_h : I \rightarrow \mathbb{R}_{\text{sym}, \geq 0}^{2 \times 2}$

If $[C_f(x)]_{22} > 0$, the unique minimizer of $\mathbb{R} \ni \alpha \mapsto H^x(t, \hat{X}_t^x, \alpha, p_t^x)$ is

$$\hat{\alpha}_t^x = \frac{1}{[C_f(x)]_{22}} \left(-[C_f(x)]_{12} \hat{X}_t^x - [C_f(x)]_{32} \hat{Z}_t^x - b(x) p_t^x \right).$$

and the corresponding FBSDE system reads

$$\begin{cases} d\hat{X}_t^x &= (\Gamma_X^0(x) \hat{X}_t^x + \Gamma_X^1(x) p_t^x + \Gamma_X^2(x) \hat{Z}_t^x) dt + dB_t^x, & X_0^x = \xi^x, \\ dp_t^x &= -(\Gamma_p^0(x) \hat{X}_t^x + \Gamma_p^1(x) p_t^x + \Gamma_p^2(x) \hat{Z}_t^x) dt + q_t^x dB_t^x, \\ p_T^x &= [C_h(x)]_{11} \hat{X}_T^x + [C_h(x)]_{12} \hat{Z}_T^x, & \hat{Z}_t^x = \int_t^T w(x, y) \mathbb{E}[\hat{X}_t^y] \lambda(dy), \end{cases} \quad (3)$$

with

$$\begin{aligned} \Gamma_X^0(x) &:= a(x) - \frac{b(x)[C_f(x)]_{12}}{[C_f(x)]_{22}}, & \Gamma_p^0(x) &:= [C_f(x)]_{11} - \frac{[C_f(x)]_{12}^2}{[C_f(x)]_{22}}, \\ \Gamma_X^1(x) &:= -\frac{b^2(x)}{[C_f(x)]_{22}}, & \Gamma_p^1(x) &:= \Gamma_X^0(x), \\ \Gamma_X^2(x) &:= c(x) - \frac{b(x)[C_f(x)]_{32}}{[C_f(x)]_{22}}, & \Gamma_p^2(x) &:= [C_f(x)]_{13} - \frac{[C_f(x)]_{12}[C_f(x)]_{32}}{[C_f(x)]_{22}}. \end{aligned}$$

It reduces to a **Riccati matrix system**

N -player Network Game

(I) Fix a sequence $x^\infty = (x_k)_{k=1}^\infty \in I^\infty$

We shall sample (with replacement) these sequences from $\lambda^\infty = \otimes_{k=1}^\infty \lambda$

(II) **Admissible strategies** for the N -player game: $\mathbb{A}_N(x^\infty)$ set of $\bigvee_{\ell=1}^N \mathbb{F}^{x_\ell}$ -progressively measurable functions in $L^2(\Omega; L^2([0, T]))$

(III) **Expected costs** for player k who picks a control $\alpha^{k,N}$ in the N -player game and the other players pick $\alpha^{-k,N}$

$$J^{k,N}(\alpha^{k,N}; \alpha^{-k,N}) = \mathbb{E} \left[\int_0^T f^{x_k}(X_t^{k,N}, \alpha_t^{k,N}, Z_t^{k,N}) dt + h^{x_k}(X_T^{k,N}, Z_T^{k,N}) \right]$$

(IV) where the **player states** $(X^{k,N})_{k=1}^N$ have the dynamics

$$dX_t^{k,N} = (a(x_k)X_t^{k,N} + b(x_k)\alpha_t^{k,N} + c(x_k)Z_t^{k,N}) dt + dB_{x_k}(t), \quad X_0^{k,N} = \xi^{x_k},$$

$$Z_t^{k,N} = \frac{1}{N} \sum_{\ell=1}^N w(x_k, x_\ell) X_t^{\ell,N}, \quad k = 1, \dots, N, \quad t \in [0, T].$$

Stochastic Maximum Principle for the N -player Game

Necessarily the equilibrium strategies must be

$$\hat{\alpha}_t^{k,N} = -\frac{1}{[C_f(x_k)]_{22}} \left(b(x_k) p_t^{kk,N} + [C_f(x_k)]_{21} X_t^{k,N} + [C_f(x_k)]_{23} Z_t^{k,N} \right),$$

and we need to solve for the N state variables $(X^{k,N})_{k=1}^N$ and the N^2 adjoint variables $(p^{kh}, (q^{kh\ell})_{\ell=1}^N)_{k,h=1}^N$

$$\left\{ \begin{array}{l} dX_t^{k,N} = \left(\Gamma_X^0(x_k) X_t^{k,N} + \Gamma_X^1(x_k) p_t^{kk,N} + \Gamma_X^2(x_k) Z_t^{k,N} \right) dt + dB_{x_k}(t), \quad X_0^{k,N} = \xi^{x_k}, \\ Z_t^{k,N} := \frac{1}{N} \sum_{\ell=1}^N w(x_k, x_\ell) X_t^{\ell,N}, \quad k = 1, \dots, N, \quad t \in [0, T] \\ dp_t^{kk,N} = - \left(\Gamma_p^0(x_k) X_t^{k,N} + \Gamma_p^1(x_k) p_t^{kk,N} + \Gamma_p^2(x_k) Z_t^{k,N} \right. \\ \quad \left. + \frac{1}{N} \sum_{\ell=1}^N c(x_\ell) w(x_k, x_\ell) p_t^{k\ell,N} \right) dt + \sum_{\ell=1}^N q_t^{kk\ell,N} dB_{x_\ell}(t), \\ p_T^{kk,N} = [C_h(x_k)]_{11} X_T^{k,N} + [C_h(x_k)]_{12} Z_T^{k,N}, \\ dp_t^{kh,N} = - \frac{w(x_k, x_h)}{N} \left(\Gamma_p^3(x_k) X_t^{k,N} + \Gamma_p^4(x_k) p_t^{kk,N} + \Gamma_p^5(x_k) Z_t^{k,N} \right) dt \\ \quad - \left(\frac{1}{N} \sum_{\ell=1}^N c(x_\ell) w(x_h, x_\ell) p_t^{k\ell,N} + a(x_h) p_t^{kh,N} \right) dt + \sum_{\ell=1}^N q_t^{kh\ell,N} dB_{x_\ell}(t), \\ p_T^{kh,N} = \frac{w(x_k, x_h)}{N} \left([C_h(x_k)]_{21} X_T^{k,N} + [C_h(x_k)]_{22} Z_T^{k,N} \right), \quad 1 \leq h \neq k \leq N, \quad t \in [0, T] \end{array} \right.$$

Propagation of Chaos

For each $x^\infty = (x_h)_{h \geq 1} \in I^\infty$, define $\zeta_N^{x^\infty}$ by

$$\zeta_N^{x^\infty} : [0, T] \times I \ni (t, x) \mapsto \frac{1}{N} \sum_{h=1}^N w(x, x_h) X_t^{x_h} - \int_I w(x, y) \mathbb{E}[X_t^y] \lambda(dy).$$

Proposition

There exists a constant $C > 0$ s.t. for all $x^\infty \in I^\infty$ and $N \geq 1$,

$$\begin{aligned} \max_{1 \leq k \leq N} \left(\mathbb{E} \left[\sup_{t \in [0, T]} (|X_t^{k, N} - X_t^{x_k}|^2 + |p_t^{k, N} - p_t^{x_k}|^2) \right] + \sup_{t \in [0, T]} \mathbb{E} \left[|Z_t^{x_k, N} - Z_t^{x_k}|^2 \right] \right) \\ \leq \sup_{(t, x) \in [0, T] \times I} C \left(\mathbb{E} \left[|\zeta_N^{x^\infty}(t, x)|^2 \right] + \frac{1}{N} \right) \end{aligned}$$

and the size of $\zeta_N^{x^\infty}$ can be controlled by a Banach space valued LIL !

For all $\varepsilon > 0$, there exists a $N_\varepsilon : I^\infty \mapsto \mathbb{N}$ such that

$$\bar{\lambda}^\infty \left[\sup_{(t, x) \in [0, T] \times I} \mathbb{E} \left[|\zeta_N^{x^\infty}(t, x)|^2 \right] \leq \frac{(C + \varepsilon)^2 \log \log N}{N}, N \geq N_\varepsilon(x^\infty) \right] = 1$$

Approximation Result

Proposition

(I) For $\varepsilon_N := 2C\sqrt{N^{-1} \log \log N}$

(II) For λ^∞ -a.e. $x^\infty = (x_k)_{k \geq 1} \in I^\infty$,

the **strategy profile** $(\hat{\alpha}^{x_k})_{k=1}^N$ given by **the graphon game Nash equilibrium** is an ε_N -Nash equilibrium for the N -player game between the players (x_1, \dots, x_N) when N is large enough (i.e. $N \geq \underline{N}(x^\infty)$).

In other words, for all $k = 1, \dots, N$ and $\beta \in \mathbb{A}_N(x^k)$:

$$J^{k,N}(\hat{\alpha}^{x_k}; \hat{\alpha}^{-k,N}) - J^{k,N}(\beta; \hat{\alpha}^{-k,N}) \leq \varepsilon_N,$$

where $\hat{\alpha}^{-k,N} := (\hat{\alpha}^{x_1}, \dots, \hat{\alpha}^{x_{k-1}}, \hat{\alpha}^{x_{k+1}}, \dots, \hat{\alpha}^{x_N})$.

This recasts this approach in one of the frameworks proposed by

Feldman-Gilles.